Mission 8 Assignment	Name:
Pre-Mission Preparation	
In the last mission the CodeBot used line sensors to detect reflected light. What do you remember about line sensors?	Answers will vary. Answers can include: CodeBot has 5 line sensors, numbered 0 to 4 They have an emitter, detector and read reflected light Line sensors return a value between 0 and 4095 Higher values = less reflective surface, like a black line Line sensors are read with ls.read(num)
Mission 8 Checks	
Objective #1 A less reflective surface, like a black line, results in values, while a more reflective surface, like a white floor, results in	Higher values Lower values
How can you clear the console window? Check the hints!	Right-click in the Console Panel and select "Terminal Clear"
Objective #2 What is your average value for the surface?	Answers will vary (could be 4095)
What is your average value for the black line?	Answers will vary (could be 286)
What value did you select for the threshold?	Answers will vary (could be 2000)
Objective #3 After adding the brake function, try different speeds. What is your top speed for staying on the board?	Answers will vary
What is the editor shortcut for commenting out a line of code? (Check the hints)	CTRL-/
Objective #4 This objective uses a default parameter. Arguments can be passed as keyword or positional. Look in the toolbox for the difference between the two.	Keyword argument: When you call a function and specify the name of the argument and its value (delay=0.5)
	Positional argument: When you call a function and put the arguments in the same order as the parameters
Objective #5 What does this code do: sensors = []	Defines an empty list
What does this code do: sensors.append(is_line)	Adds an item (or value) to the end of a list
What is returned at the end of the new function?	A list of 5 Boolean values



Objective #6 What is used to turn on the line sensor LEDs?	The list of 5 Boolean values
What does the built-in function any() do?	It is a function that returns True if any item in the list is True.
Post-Mission Reflection	
What is something you learned about yourself during this mission?	Answers will vary
This mission will use sensors to keep the CodeBot inside the lines. We participate in many activities that require us to stay in a well-defined area. Sports, for example. List some activities that or real-world applications that have boundaries:	 Answers will vary Airplanes have to stay on the airstrip In sports, players and/or the ball need to stay in bounds In stores, you have to stay in the aisles At school you have boundaries

